

Representations of Logic Functions using QRMDDs

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Abstract

This paper considers quasi-reduced multi-valued decision diagrams with k bits (QRMDD(k))s to represent two-valued logic functions. It shows relations between the numbers of nodes in QRMDD(k))s and values of k for benchmark functions; an upper bound on the number of nodes in the QRMDD(k); difference between the upper bound and the number of nodes in the QRMDD(k))s for random functions; and the amount of total memory, evaluation time, and area-time complexity for QRMDD(k))s. Experimental results using standard benchmark functions show that the area-time complexity takes its minimum when k is between 3 and 6.

1. Introduction

With the increase of the complexity of digital systems, representations of logic functions that can evaluate functions efficiently and require small amount of memory are becoming important [2]. In this paper, we consider representations of two-valued logic functions using quasi-reduced multi-valued decision diagrams with k bits (QRMDD(k))s. As for methods to represent logic functions by decision diagrams (DDs), binary decision diagrams (BDDs) [1, 7] and multi-valued decision diagrams (MDDs) [3, 10, 12, 14] are known. Especially, MDDs require fewer nodes than corresponding BDDs. Also, the number of memory accesses required in MDDs is smaller than corresponding BDDs [12]. In this paper, we show relations among the amount of memory to represent QRMDD(k), the number of memory accesses, and values of k .

The rest of the paper is organized as follows:

In Section 2, we will define MDDs and QRMDDs, and explain benchmark functions and random functions.

In Section 3, we obtain an upper bound on the number of nodes in a QRMDD(k). Also, we show an interesting

property holds for many of benchmark functions. We also show that random functions do not have this property.

In Section 4, we introduce the measure called *area-time complexity*. When we use a QRMDD(k), the number of memory accesses decreases with k , while the amount of memory to represent it increase with k . We are interested in k that reduces the number of memory accesses without increasing the amount of memory excessively. To obtain such k , we introduce a measure called *area-time complexity*. By experiments, the measure is the minimum when k is between 3 and 6.

2 Definitions

This section defines quasi-reduced multi-valued decision diagrams(QRMDDs), shows a method to represent multiple-output functions, and introduces benchmark functions.

2.1 Representation of Logic Functions

Let $f(X)$ be a two-valued logic function, where $X = (x_1, x_2, \dots, x_n)$. Let $x_i (i = 1, 2, \dots, n)$ be binary variables, where $n = rk$.

Let $X = (X_1, X_2, \dots, X_r)$ be a partition of X , where $\{X\} = \{X_1\} \cup \{X_2\} \cup \dots \cup \{X_r\}$ and $\{X_i\} \cap \{X_j\} = \emptyset (i \neq j)$, and each X_j consists of k binary variables. Then, a two-valued logic function $f(X)$ can be represented by $f(X_1, X_2, \dots, X_r): \{0, 1, 2, \dots, 2^k - 1\}^r \rightarrow B$, where $B = \{0, 1\}$.

2.2 QRMDD

As for the definitions on MDDs, refer [10].

Definition 2.1 *The reduced ordered multi-valued decision diagram (RMDD) having non-terminal nodes with 2^k edges is denoted by RMDD(k). Especially, when $k = 1$, RMDD(1) is a reduced ordered binary decision diagram (RBDD).*

Definition 2.2 *In a decision diagram (DD), a path from the root node to a terminal node is a **path of DD**. The number of edges on the path is the **length of the path**.*

Definition 2.3 In a DD, the **number of nodes in the DD**, denoted by $nodes(DD)$, includes terminal nodes.

Definition 2.4 When all X_i ($i = 1, 2, \dots, u$) appear in this order on an arbitrary path of an $MDD(k)$, the $MDD(k)$ is a **quasi-reduced multi-valued decision diagram with k bits** ($QRMDD(k)$).

The length of an arbitrary path in a $QRMDD(k)$ is equal to u , the number of input variables. An RMDD has no redundant nodes, while a QRMDD usually has redundant nodes. Therefore, we have the following relation in the number of nodes of an RMDD and its corresponding QRMDD:

$$nodes(RMDD(k)) \leq nodes(QRMDD(k)).$$

In general, QRMDDs (QRBDDs) require more nodes than corresponding RMDDs (RBDDs). However, QRMDDs (QRBDDs) have the following features:

1. When the RBDDs are too large to be store in the main memory, QRBDDs can be processed much faster than corresponding RBDDs [15].
2. QRBDDs can be manipulated efficiently by parallel processors [16].
3. QRBDDs (QRMDDs) are used to design LUT cascades [22].

The most severe limitation of conventional BDDs is their size. When a BDD does not fit in the main memory, the BDD must use the secondary memory. This will increase the number of page faults, and access to the secondary memory [24]. In such a case, quasi-reduced decision diagrams can be used to reduce the page faults. This approach is useful when the quasi-reduced decision diagram is not so greater than the corresponding reduced decision diagrams.

Definition 2.5 Let the input variables be $X = (X_1, X_2, \dots, X_u)$. Consider a $QRMDD$ for a function $f(X)$. The number of non-terminal nodes in the $QRMDD$ with respect to a variable X_i is **width of the QRMDD with respect to X_i** , and denoted by $width(QRMDD(k), i)$.

The total number of nodes in the $QRMDD(k)$ is given by

$$nodes(QRMDD(k)) = \sum_{i=1}^u width(QRMDD(k), i).$$

Example 2.1 Consider the function:

$$f = x_1 x_2 x_3 \vee x_2 x_3 x_4 \vee x_3 x_4 x_1 \vee x_4 x_1 x_2.$$

The RBDD, the RMDD(2), and the QRMDD(2) for f are shown in Fig. 2.1(a), Fig. 2.1(b), and Fig. 2.2, respectively. In Fig. 2.1(a), the solid lines and the broken lines denote 1-edges and 0-edges, respectively. In Fig. 2.1(b), the input variables $X = (x_1, x_2, x_3, x_4)$ are partitioned into $X = (X_1, X_2)$, where $X_1 = (x_1, x_2)$ and $X_2 = (x_3, x_4)$. We have $nodes(RBDD) = 8$, $nodes(RMDD(2)) = 5$, and $nodes(QRMDD(2)) = 6$. Note that $width(QRMDD(2), 2) = 3$. (End of Example)

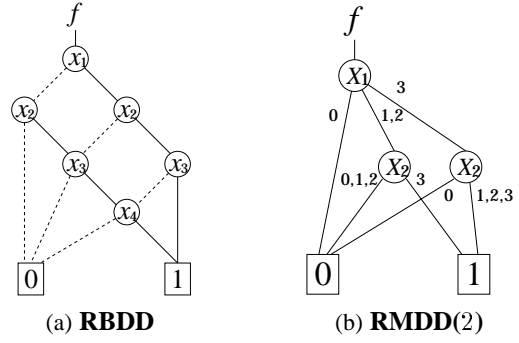


Figure 2.1. DDs.

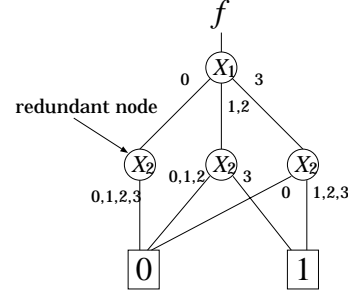


Figure 2.2. QRMDD(2).

2.3 Representations of Multiple-Output Functions

Logic networks usually have many outputs. In most cases, independent representation of each output is inefficient. Let the multiple-output functions be $F = (f_0, f_1, \dots, f_{m-1}): B^n \rightarrow B^m$, where $B = \{1, 0\}$, and n and m denote the number of inputs and outputs, respectively. Several methods exist to represent multiple-output functions by using BDDs [13, 18, 19, 20]. In this paper, we use an encoded characteristic function for non-zero output (ECFN) [21] to represent multiple-output functions. In the following, an RBDD means a BDD for an ECFN, and we assume that RMDDs and QRMDDs are generated from these RBDDs.

2.4 Benchmark Functions

In this paper, we use 131 benchmark functions [6, 25] shown in Table 2.1, where n and m denote the number of inputs and outputs, respectively. In this table, the benchmark functions under *sequential* originally represent sequential circuits. We removed flip-flops (FFs) from sequential circuits to make them combinational. Such functions are renamed by appending 'c' to the original names. Encodings of BDDs for ECFNs and input variable orderings are obtained in [22]. Details of experimental results are omitted due to the page limitation.

Table 2.1. Benchmark Functions.

Name	n	m	Name	n	m	Name	n	m
C432	36	7	frg1	28	3	soar	83	94
C499	41	32	frg2	143	139	spla	16	46
C880	60	26	i1	25	16	t1	21	23
C1355	41	32	i2	201	1	t2	17	16
C1908	33	25	i3	132	6	table5	17	15
C2670	233	140	i4	192	6	tcon	17	16
C3540	50	22	i5	133	66	term1	34	10
C5315	178	123	i6	138	67	ti	47	72
C7552	207	108	i7	199	67	too_large	38	3
accpla	50	69	i8	133	81	ts10	22	16
al2	16	47	i9	88	63	ttt2	24	21
alcom	15	38	i10	257	224	unreg	36	16
apex1	45	45	ibm	48	17	vda	17	39
apex2	39	3	in1	16	17	vg2	25	8
apex3	54	50	in2	19	10	vtx1	27	6
apex5	117	88	in3	35	29	x1	51	35
apex6	135	99	in4	32	20	x3	135	99
apex7	49	37	in5	24	14	x4	94	71
b2	16	17	in6	33	23	x1dn	27	6
b3	32	20	in7	26	10	x2dn	82	56
b4	33	23	jbp	36	57	x6dn	39	5
b9	41	21	k2	45	45	x7dn	66	15
bc0	26	11	lal	26	19	x9dn	27	7
bca	26	46	mainpla	27	54	xparc	41	73
bcb	26	39	mark1	20	31	sequential		
bcc	26	45	misex2	25	18	s208c	18	9
bcd	26	38	misg	56	23	s298c	17	20
c8	28	18	mish	94	43	s344c	24	26
cc	21	20	misj	35	14	s349c	24	26
chkn	29	7	mlp10	20	20	s382c	24	27
cht	47	36	mux	21	1	s400c	24	27
cm150a	21	1	my_adder	33	17	s420c	34	17
comp	32	3	opa	17	69	s444c	24	27
cordic	23	2	pair	173	137	s510c	25	13
count	35	16	pcle	19	9	s526c	24	27
cps	24	109	pcler8	27	17	s641c	54	43
dalu	75	16	pdc	16	40	s713c	54	42
des	256	245	pm1	16	13	s820c	23	24
dk48	15	17	rckl	32	7	s832c	23	24
duke2	22	29	rot	135	107	s838c	66	33
e64	65	65	sct	19	15	s1196c	32	32
ex4	128	28	seq	41	35	s1423c	91	79
example2	85	66	shift	19	16	s5378c	214	228
exep	30	63	signet	39	8	s9234c	247	250

3 Number of Nodes in QRMDD(k)

In this part, we first obtain an upper bound on the number of nodes in a QRMDD(k). Then, we obtain the sizes of QRMDD(k)s for benchmark functions, and show that an interesting property holds for many of them. Finally, we obtain the sizes of QRMDD(k)s for randomly generated logic functions, and show that they can be estimated by the upper bound.

3.1 General Functions

For arbitrary logic functions, we have the following:

Theorem 3.1 *An arbitrary n -input logic function can be represented by a QRBDD with at most*

$$2^{n-r} - 1 + \sum_{i=0}^r 2^{2^i}$$

Table 3.1. Relation of nodes in QRMDD(k) and k for benchmark functions.

	k				
	1	2	3	4	5
ave	1.00	0.50	0.33	0.25	0.20
stdv	0.000	0.014	0.007	0.013	0.009

Table 3.2. functions with $\eta \geq 0.1$

Name	Circuit	Name	Circuit
C499	error_correcting	my_adder	adder
C1908	error_correcting	pcle	control
comp	comparator	tcon	control
i3	control	vg2	control
in1	control	vtx1	control
mlp10	multiplier	x1dn	control

nodes, where r is the largest integer that satisfies relation

$$n - r \geq 2^r.$$

Theorem 3.2 *An arbitrary n -input logic function can be represented by a QRMDD(k) with at most*

$$\frac{2^{sk} - 1}{2^k - 1} + \sum_{i=0}^{t-1} 2^{2^{n-(s+i)k}} + 2$$

nodes, where s and t are the smallest integer that satisfy relations

$$s \geq \frac{n-r}{k}, \quad t \geq \frac{n}{k} - s.$$

The proofs of Theorem 3.1 and Theorem 3.2 are shown in Appendix.

3.2 Benchmark Functions

For each benchmark function in Table 2.1, we counted the number of nodes in QRMDD(k)s for different k . In Table 3.1, *ave* denotes arithmetic average of the relative sizes, where the number of nodes in QRMDD(1) is set to 1.00, and *stdv* denotes the standard deviation. We consider the following:

$$\eta = \left| 1 - \frac{k \cdot \text{nodes}(\text{QRMDD}(k))}{\text{nodes}(\text{QRMDD}(1))} \right|.$$

Since 119 functions out of 131 functions in Table 2.1 satisfy the relation $\eta < 0.1$, we have

Property 3.1

$$\text{nodes}(\text{QRMDD}(k)) \simeq \frac{1}{k} \text{nodes}(\text{QRMDD}(1))$$

Property 3.1 holds for the 119 functions in Table 2.1. As for remaining 12 functions, $\eta \geq 0.1$ holds. Table 3.2 lists these 12 functions. Note that Table 2.1 does not contain functions having small inputs and outputs.

Table 3.3. The number of nodes in QRMDD(k) for random functions.

n	k				
	1	2	3	4	5
10	249.4	103.0	79.0	35.0	35.0
11	439.1	253.2	91.0	181.2	39.0
12	756.0	358.5	298.5	274.5	51.0
13	1294.8	598.6	589.2	279.0	286.6
14	2318.0	1376.1	603.0	291.0	1052.1
15	4343.1	1627.0	843.0	531.0	1059.0
16	8338.5	5348.5	4556.5	4240.5	1063.0
17	16167.3	5723.0	4699.0	4375.0	1075.0
18	31157.9	19975.9	4939.0	4387.0	1315.0
19	58838.4	22107.0	30480.4	4627.0	26852.4
20	107222.3	63272.3	37467.0	45780.3	33827.0

Table 3.4. Upper bound on the number of nodes in QRMDD(k)s.

n	k				
	1	2	3	4	5
10	277	103	79	35	35
11	533	347	91	275	39
12	789	359	331	275	51
13	1301	603	591	279	291
14	2325	1383	603	291	1060
15	4373	1627	843	531	1059
16	8469	5479	4687	4371	1063
17	16661	5723	4699	4375	1075
18	33045	21863	4939	4387	1315
19	65813	22107	37455	4627	33828
20	131349	87399	37467	69907	33827

3.3 Random Functions

We examined whether Property 3.1 holds for random functions. For each n , we randomly generated 2^{n-1} minterms. Table 3.3 shows average numbers of nodes in QRMDD(k)s for n -input random functions. For each n , we generated 10 samples. The deviation of each data is within $\pm 2\%$ of the averages. Table 3.4 shows upper bounds on the numbers of nodes in QRMDD(k)s derived from Theorem 3.2.

The ratio of difference γ between upper bounds and experimental results on the number of nodes in QRMDD(1) for n -input random functions is computed as follows:

$$\gamma = \frac{\text{upper bound} - \text{experimental result}}{\text{upper bound}} \times 100$$

Table 3.5 shows that γ is large after r changes, and is small in other cases. This means that the size of QRMDD(k) for randomly generated functions can be estimated by Theorem 3.2. Table 3.3 also shows that Property 3.1 doesn't hold for random functions. This fact shows that benchmark functions have quite different property from random functions.

Table 3.5. Ratio of difference γ for random functions.

n	r	$\gamma(\%)$	n	r	$\gamma(\%)$	n	r	$\gamma(\%)$
5	1	25.24	12	3	4.81	19	3	10.60
6	2	28.11	13	3	0.48	20	4	18.37
7	2	16.42	14	3	0.30	21	4	4.50
8	2	12.00	15	3	0.68	22	4	0.37
9	2	11.07	16	3	1.54	23	4	0.00
10	2	9.96	17	3	2.96	24	4	0.00
11	3	17.62	18	3	5.71	25	4	0.01

4 Area-Time Complexity of QRMDD(k)

When we use QRMDD(k), the amount of memory access decreases with k , while the total amount of memory increases with k . Thus, we are interested in finding k that reduces the number of memory access without increasing the total amount of memory excessively. To obtain such k , we introduce a measure called *area-time complexity*.

4.1 Model of Computation

We assume the followings:

1. MDDs are implemented directly, not simulated by using BDD packages [10].
2. Encoded input values are available as inputs, and their access time is negligible. For example, when $X_1 = (x_1, x_2, x_3, x_4) = (1, 0, 0, 1)$, $X_1 = 9$ is available as an input.
3. Access to the MDD nodes is time-consuming.

In this case, the computation time is proportional to the number of access to the MDD nodes.

4.2 Amount of Memory to Represent QRMDD(k)

Because QRMDD(k) evaluates variables X_1, X_2, \dots, X_u in this order, we can use a counter to obtain the next variable to evaluate. Therefore, when a QRMDD(k) is stored in a memory, we need not store an index in a node, but have only to store the next addresses. On the other hand, in an RMDD(k), we have to store an index and the next addresses because the next variable to evaluate may be different in different paths.

Example 4.1 Fig. 4.1 and Fig. 4.2 illustrate data structures of a node in a QRMDD(2) and an RMDD(2), respectively. (End of Example)

Because each node in a QRMDD(k) has 2^k edges, we need

$$2^k \text{nodes}(\text{QRMDD}(k))$$

words to represent all nodes in a QRMDD(k). When a DD is stored in a memory, each node requires a unique address. The number of bits necessary to specify the address of a node is

$$\lceil \log_2 \text{nodes}(\text{DD}) \rceil.$$

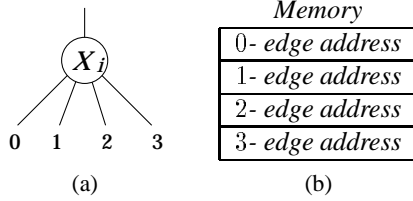


Figure 4.1. Data structure of a node in QRMDD(2).

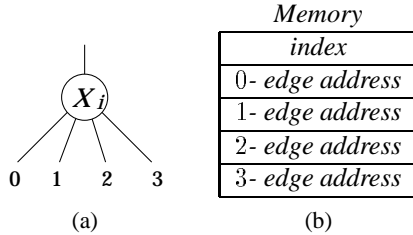


Figure 4.2. Data structure of a node in RMDD(2).

Therefore, the total amount of memory to represent a QRMDD(k) is

$$2^k \text{nodes}(\text{QRMDD}(k)) \lceil \log_2 \text{nodes}(\text{QRMDD}(k)) \rceil.$$

4.3 Area-Time Complexity of QRMDD(k)s

Because a QRMDD(k) evaluates k variables at a time, the number of memory accesses of a QRMDD(k) is $\frac{1}{k}$ of the corresponding QRMDD(1). On the other hand, the amount of memory necessary to store a QRMDD(k) node increases with 2^k . In this section, we consider the area-time complexity [5, 23] for QRMDD(k) and obtain the k that minimizes the area-time complexity.

Definition 4.1 The area-time complexity is the measure of computational cost considering both area and time. It is defined by

$$AT = (\text{area}) \times (\text{time}),$$

or

$$AT^2 = (\text{area}) \times (\text{time})^2.$$

Table 4.1. Relation of k and A for QRMDD(k) for benchmark functions.

	k				
	1	2	3	4	5
<i>ave</i>	1.00	0.91	1.14	1.65	2.54
<i>stdv</i>	0.000	0.036	0.070	0.114	0.190

Table 4.2. Relation of k and AT for QRMDD(k) for benchmark functions.

	k				
	1	2	3	4	5
<i>ave</i>	1.00	0.46	0.39	0.43	0.53
<i>stdv</i>	0.000	0.019	0.027	0.032	0.047

Table 4.3. Relation of k and AT^2 for QRMDD(k) for benchmark functions.

	k						
	1	2	3	4	5	6	7
<i>ave</i>	1.000	0.233	0.133	0.112	0.113	0.131	0.166
<i>stdv</i>	0.000	0.011	0.011	0.011	0.014	0.023	0.029

In this paper, the area corresponds to the necessary amount of memory to represent a QRMDD(k), and the time corresponds to the number of memory accesses to evaluate it.

The measure AT is used when both the amount of memory and the number of memory accesses are equally important. On the other hand, the measure AT^2 is used when the number of memory accesses is more important than the amount of memory. For example, AT can be used for embedded systems [2], while AT^2 can be used for logic simulators [8, 9].

4.4 Experimental Results

For each benchmark function in Table 2.1, we obtained three measures A , AT , and AT^2 . Table 4.1, Table 4.2, and Table 4.3 show the relation of k and A , AT , and AT^2 , respectively. In these tables, *ave* denotes the arithmetic average, and *stdv* denotes the standard deviation for benchmark functions.

For each benchmark function in Table 2.1, A takes its minimum when $k = 2$; AT takes its minimum when $k = 3$ or $k = 4$; and AT^2 takes its minimum when $k = 4 \sim 6$.

4.5 Analysis for the Functions that Satisfy Property 3.1

In Section 4.4, for QRMDD(k)s, we found values of k that make A , AT and AT^2 minimum, experimentally. In this section, we assume that Property 3.1 holds, and will find the values k that make A , AT and AT^2 minimum, analytically. Let A and T be the necessary amount of memory to represent a QRMDD(k), and the number of memory accesses necessary to evaluate a QRMDD(k), respectively. Then, we have the following:

$$A = 2^k \text{nodes}(\text{QRMDD}(k)) \lceil \log_2 \text{nodes}(\text{QRMDD}(k)) \rceil,$$

$$T = \lceil \frac{n}{k} \rceil.$$

Let assume that Property 3.1 holds and $n_{\text{odes}}(\text{QRMD}(1)) = N$. Then we have:

$$A \simeq \frac{2^k}{k} N \lceil \log_2 \frac{N}{k} \rceil,$$

$$AT \simeq \frac{2^k n}{k^2} N \lceil \log_2 \frac{N}{k} \rceil,$$

and

$$AT^2 \simeq \frac{2^k n^2}{k^3} N \lceil \log_2 \frac{N}{k} \rceil.$$

Note that N is usually greater than a few hundreds, while k is usually at most 7. Thus, we can use the following approximation:

$$\lceil \log_2 N - \log_2 k \rceil \simeq \lceil \log_2 N \rceil.$$

Therefore, A , AT and AT^2 can be simplified to

$$A \simeq \frac{2^k}{k} C_0, \quad AT \simeq \frac{2^k}{k^2} C_1, \quad \text{and} \quad AT^2 \simeq \frac{2^k}{k^3} C_2,$$

respectively, where the constants C_0 , C_1 and C_2 are independent of k . From the above formulas, we can see that A , AT and AT^2 take their minimum when $k = 2$, $k = 3$ and $k = 4$, respectively.

5 Conclusion and Comments

In this paper, we considered a method to represent logic functions by using QRMD(k)s. Especially, 1) We derived an upper bound on the number of nodes in a QRMD(k), and showed that the numbers of nodes in QRMD(k)s for random functions can be estimated by the bound, 2) We showed that Property 3.1 holds for many benchmark functions, and 3) We showed that the area-time complexity for QRMD(k) takes its minimum when $k = 3 \sim 6$, and 4) We showed that benchmark functions have quite different property from randomly generated functions.

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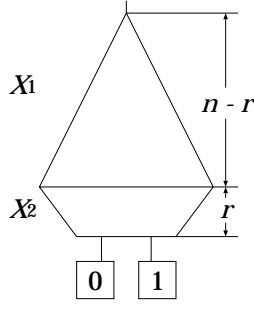


Figure A.1. Partition of BDD.

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A Appendix

A.1 Proof of Theorem 3.1

Definition A.1 Suppose that a quasi-reduced ordered binary decision diagram (QRBDD) for an n -input logic function is partitioned into two parts as shown in Fig A.1. It is partitioned into **the upper part** and **the lower part**. The upper part has the variables $X_1 = (x_1, x_2, \dots, x_{n-r})$, while the lower part has the variables $X_2 = (x_{n-r+1}, \dots, x_n)$.

Proof of Theorem 3.1 The number of non-terminal nodes in the complete binary tree for n variables is $2^n - 1$. This gives the number of nodes in the upper part. As for the lower part, the width of QRBDD becomes narrow because the nodes representing the same functions are deleted. The upper bound on the number of nodes in a BDD becomes minimum when r is the maximum integer satisfying $n - r \geq 2^r$ [11]. As for the lower part, at most 2^{2^r} r -input logic functions are represented. When all of these functions are represented, the number of nodes in the lower part becomes maximum. In this case, the BDD represents the logic function as follows:

$$f(X_1, X_2) = \bigvee_{\vec{a}_i \in B^{n-r}} X_1^{\vec{a}_i} f(\vec{a}_i, X_2),$$

where

$$X_1^{\vec{a}_i} = \begin{cases} 1 & (X_1 = \vec{a}_i) \\ 0 & (\text{otherwise}) \end{cases}.$$

The upper part realizes $X_1^{\vec{a}_i}$, and the lower part realizes $f(\vec{a}_i, X_2)$. Because $f(\vec{a}_i, X_2)$ is an r -input logic function, at most 2^{2^r} different $f(\vec{a}_i, X_2)$ exist in the lower part. When 2^{2^i} functions are realized for each i ($i = 0, \dots, r$) from the terminal node to the r , the QRBDD has the maximum number of nodes. Therefore, the number of nodes in a QRBDD is at most

$$2^{n-r} - 1 + \sum_{i=0}^r 2^{2^i}.$$

(Q.E.D)

A.2 Proof of Theorem 3.2

First, we will consider Lemma A.1 to prove Theorem 3.2.

Lemma A.1 Let an n -input logic function be $f(X)$, where $X = (x_1, x_2, \dots, x_n)$. Let $f(X)$ be decomposed as

$$f(X) = g_i(h(X_1, X_2, \dots, X_i), X_{i+1}, \dots, X_u),$$

where $u = \lceil \frac{n}{k} \rceil$, and let μ_i be the column multiplicity of the decomposition for $i = 1, 2, \dots, u$. Then, the number of nodes in the QRMDD(k) for f is given by

$$\text{nodes}(\text{QRMDD}(k)) = \sum_{i=1}^u \mu_i.$$

Proof Since the width of the QRMDD(k) with respect to a variable X_i is equal to the column multiplicity μ_i [17, 18], we have the lemma. (Q.E.D)

Proof of Theorem 3.2 By Lemma A.1, the number of nodes in a QRMDD(k) for an n -input logic function is equal to the sum of the column multiplicities that are obtained by iterative functional decompositions. The upper part of the QRBDD is decomposed into s parts. In this case, $\mu_1, \mu_2, \dots, \mu_s$ are $1, 2^k, 2^{2k}, \dots, 2^{sk}$. It is a geometric progression with the initial term 1 and the common ratio 2^k . The lower part of the QRBDD is decomposed into t parts. Also in the lower part, the number of nodes is equal to the sum of the column multiplicities. In other words, it is equal to the sum of the widths of a QRBDD with respect to corresponding variables. When $n \neq (s+t)k$, the number of variables in X_u is not a multiple of k . So, the column multiplicity for this part is computed separately. Note that $\mu_u = 2$, since f is a two-valued logic function. Thus, the number of nodes in QRMDD(k) is at most

$$\frac{2^{sk} - 1}{2^k - 1} + \sum_{i=0}^{t-1} 2^{2^{n-(s+i)k}} + 2.$$

(Q.E.D)