

BDD Representation for Incompletely Specified Multiple-Output Logic Functions and Its Applications to the Design of LUT Cascades

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SUMMARY A multiple-output function can be represented by a binary decision diagram for characteristic function (BDD_for_CF). This paper presents a method to represent multiple-output incompletely specified functions using BDD_for_CFs. An algorithm to reduce the widths of BDD_for_CFs is presented. This method is useful for decomposition of incompletely specified multiple-output functions. Experimental results for radix converters, adders, a multiplier, and lists of English words show that this method is useful for the synthesis of LUT cascades. An implementation of English words list by LUT cascades and an auxiliary memory is also shown.

key words: *incompletely specified function, characteristic function, binary decision diagram, functional decomposition, LUT cascade*

1. Introduction

Construction of a Binary Decision Diagram (BDD) for an incompletely specified Boolean function arises in several applications in the CAD domain: verification, logic synthesis, and software synthesis. Three methods are known to represent an incompletely specified logic function by binary decision diagrams (BDDs) [9]:

1. A ternary function that takes 0, 1 and *don't care* [9].
2. A pair of BDDs to represent three values [4].
3. An auxiliary variable that represents *don't cares* [3], [9].

Most works are related to the minimization of total number of nodes in BDDs [3], [6], [20], [21]. However, these methods are unsuitable for functional decompositions of multiple-output functions. In a functional decomposition, the minimization of width of a BDD is more important than the minimization of total number of nodes. To find an efficient decomposition of a multiple-output logic function, we can use a multi-terminal binary decision diagram (MTBDD), or a BDD that represents the characteristic function of the multiple-output function (BDD_for_CF) [15]. BDD_for_CFs usually require fewer nodes than corresponding MTBDDs, and the widths of the BDD_for_CFs tend to be smaller than that of the corresponding MTBDDs.

In this paper, we show a new method to represent an incompletely specified multiple-output function. It uses

a BDD_for_CF, and is suitable for functional decomposition. We also show a method to reduce the width of the BDD_for_CF. Experimental results using radix converters, adders, a multiplier, and English word lists show the effectiveness of the approach. A preliminary version of this paper has been published as [17].

2. Definitions

Definition 2.1: x is a support variable of f if f depends on x . A function $f : \{0, 1\}^n \rightarrow \{0, 1, d\}$ is an incompletely specified function, where d denotes the *don't care*. Let f_{-0} , f_{-1} , and f_{-d} be the functions represented by sets $f^{-1}(0)$, $f^{-1}(1)$, and $f^{-1}(d)$, respectively. Note that $f_{-0} \vee f_{-1} \vee f_{-d} = 1$, $f_{-0} \cdot f_{-1} = 0$, $f_{-1} \cdot f_{-d} = 0$, and $f_{-0} \cdot f_{-d} = 0$.

Definition 2.2: [2] Let $F = (f_1(X), f_2(X), \dots, f_m(X))$ be a multiple-output function, and let $X = (x_1, x_2, \dots, x_n)$ be the input variables. The characteristic function of the completely specified multiple-output function F is

$$\chi(X, Y) = \bigwedge_{i=1}^m (y_i \equiv f_i(X)),$$

where y_i is the variable representing the output f_i , and $i \in \{1, 2, \dots, m\}$.

The characteristic function of a completely specified multiple-output function denotes the set of the valid input-output combinations. Let $f_{i-0}(X) = \bar{f}_i(X)$ and $f_{i-1}(X) = f_i(X)$, then the characteristic function χ is represented as follows:

$$\chi(X, Y) = \bigwedge_{i=1}^m \{\bar{y}_i \cdot f_{i-0}(X) \vee y_i \cdot f_{i-1}(X)\}$$

In an incompletely specified function, when the function value f_i is *don't care*, the value of the function can be either 0 or 1. Therefore, for such inputs, the characteristic function is independent of the values of output variables y_i . Let f_{i-d} denote the *don't care* set, then we have

$$\begin{aligned} & \bar{y}_i(f_{i-0}(X) \vee f_{i-d}(X)) \vee y_i(f_{i-1}(X) \vee f_{i-d}(X)) \\ & = \bar{y}_i f_{i-0}(X) \vee y_i f_{i-1}(X) \vee f_{i-d}(X) \end{aligned}$$

Thus, we have the following:

Definition 2.3: The characteristic function χ of an incompletely specified multiple-output function $F = (f_1(X), f_2(X), \dots, f_m(X))$ is

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Table 1 Truth table of an incompletely specified function.

x_1	x_2	x_3	x_4	f_1	f_2	x_1	x_2	x_3	x_4	f_1	f_2
0	0	0	0	d	1	1	0	0	0	0	1
0	0	0	1	d	1	1	0	0	1	0	1
0	0	1	0	0	0	1	0	1	0	1	0
0	0	1	1	0	0	1	0	1	1	1	0
0	1	0	0	d	d	1	1	0	0	1	d
0	1	0	1	d	d	1	1	0	1	1	d
0	1	1	0	1	0	1	1	1	0	d	0
0	1	1	1	1	1	1	1	1	1	d	1

$$\chi(X, Y) = \bigwedge_{i=1}^m \{ \bar{y}_i f_{i,0}(X) \vee y_i f_{i,1}(X) \vee f_{i,d}(X) \}$$

Example 2.1: Consider the incompletely specified function shown in Table 1. Since,

$$\begin{aligned} f_{1,0} &= \bar{x}_1 \bar{x}_2 x_3 \vee x_1 \bar{x}_2 \bar{x}_3 \\ f_{1,1} &= \bar{x}_1 x_2 x_3 \vee x_1 \bar{x}_2 x_3 \vee x_1 x_2 \bar{x}_3 \\ f_{1,d} &= \bar{x}_1 \bar{x}_3 \vee x_1 x_2 x_3 \\ f_{2,0} &= \bar{x}_1 \bar{x}_2 x_3 \vee x_1 \bar{x}_2 x_3 \vee x_2 x_3 \bar{x}_4 \\ f_{2,1} &= \bar{x}_2 \bar{x}_3 \vee x_2 x_3 x_4 \\ f_{2,d} &= x_2 \bar{x}_3, \end{aligned}$$

the characteristic function is

$$\begin{aligned} \chi &= \{ \bar{y}_1 (\bar{x}_1 \bar{x}_2 x_3 \vee x_1 \bar{x}_2 \bar{x}_3) \vee \\ & y_1 (\bar{x}_1 x_2 x_3 \vee x_1 \bar{x}_2 x_3 \vee x_1 x_2 \bar{x}_3) \vee (\bar{x}_1 \bar{x}_3 \vee x_1 x_2 x_3) \} \\ & \cdot \{ \bar{y}_2 (\bar{x}_1 \bar{x}_2 x_3 \vee x_1 \bar{x}_2 x_3 \vee x_2 x_3 \bar{x}_4) \vee \\ & y_2 (\bar{x}_2 \bar{x}_3 \vee x_2 x_3 x_4) \vee (x_2 \bar{x}_3) \} \end{aligned}$$

(End of Example)

Next, we will consider the BDD that represents the characteristic function for an incompletely specified multiple-output function.

Definition 2.4: The BDD_for_CF of a multiple-output function $F = (f_1, f_2, \dots, f_m)$ represents the characteristic function χ of F , where the variable representing the output y_i is in the below of the support variables for f_i . (We assume that the root node is in the top.)

Figure 1 illustrates a BDD_for_CF of an incompletely specified multiple-output function, where solid lines denote the 1-edges, while dotted lines denote the 0-edges. When the 1-edge of the node y_i is connected to a constant 0 node, $f_i = 0$ (Fig. 1(a)); when the 0-edge of the node y_i is connected to a constant 0 node, $f_i = 1$ (Fig. 1(b)); and when both the 0-edge and 1-edge of the node y_i are connected to the same node except for the constant 0 node, $f_i = d$ (*don't care*) (Fig. 1(c)). In the case of $f_i = d$, the node for y_i is redundant, and it is deleted during the minimization of the BDD.

In the case of a BDD_for_CF representing a completely specified function, each path from the root node to the constant 1 node involves nodes for all the output variables y_i . Furthermore, one of the edges of the node for y_i is connected to the constant 0 node. On the other hand, in the case of a

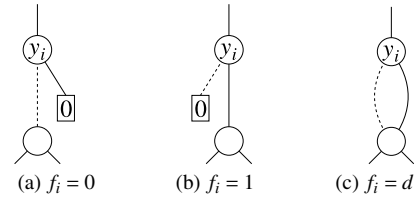


Fig. 1 BDD_for_CF representing an incompletely specified function.

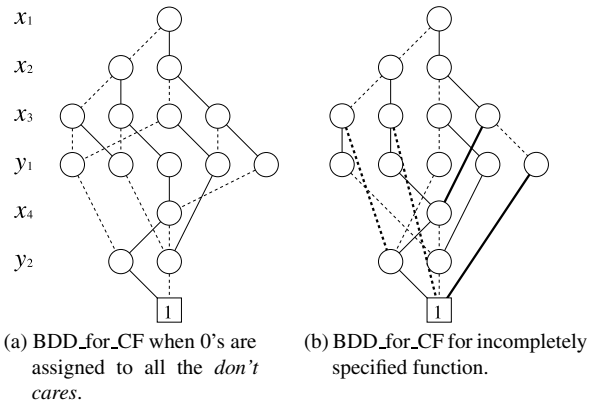


Fig. 2 BDD_for_CF representing multiple-output function.

BDD_for_CF representing an incompletely specified function, each path from the root node to the constant 1 node may not involve nodes for some variable y_i . For the path where the output variables y_i is missing, f_i is *don't care*.

Example 2.2: Figure 2 shows two BDD_for_CFs representing the function in Example 2.1. For simplicity, the constant 0 node and all the edges connecting to it are omitted. Figure 2(a) shows the BDD_for_CF representing the completely specified function where 0's are assigned to all the *don't cares*. Figure 2(b) shows the BDD_for_CF representing the incompletely specified function. The solid and dotted bold edges denote that at least one node for output variables is missing, and the output value is *don't care*. Note that in Fig. 2(a), all the output variables $\{y_1, y_2\}$ appear in each path from the root node to the constant 1 node. On the other hand, in Fig. 2(b), in the bold edges at least one output variable y_i is missing, and the corresponding output f_i is *don't care*. (End of Example)

3. Decomposition and BDD_for_CFs

3.1 Decomposition Using BDD_for_CF

By using a BDD_for_CF, we can decompose a multiple-output logic function efficiently [15]. When we decompose the function by using a BDD, the smaller the width of the BDD, the smaller the network becomes after decomposition. In the case of an incompletely specified function, we can often reduce the width of the BDD_for_CF by finding an appropriate assignment of constants to the *don't cares*. From here, we will consider a method to reduce the width of a

Table 2 Decomposition chart of an incompletely specified function.

		$X_1 = \{x_1, x_2\}$			
		00	01	10	11
$X_2 = \{x_3, x_4\}$	00	0	0	d	1
	01	1	1	d	d
	10	d	1	0	d
	11	0	d	0	0
		Φ_1	Φ_2	Φ_3	Φ_4

BDD_for_CF representing an incompletely specified function.

Definition 3.5: Let the height of the root node be the total number of variables, and let the height of the constant node be 0. Let $(z_{n+m}, z_{n+m-1}, \dots, z_1)$ be the ordering of the variables, where z_{n+m} corresponds to the variable for the root node. The width of the BDD_for_CF at the height k is the number of edges crossing the section of the BDD between variables z_k and z_{k+1} , where the edges incident to the same node are counted as one, also the edges pointing the constant 0 are not counted. The width of the BDD_for_CF at the height 0 is defined as 1.

Definition 3.6: Let $f(X)$ be a logic function, and (X_1, X_2) be a partition of the input variables. Let $|X|$ be the number of elements in X . The decomposition chart for f is a two-dimensional matrix with $2^{|X_1|}$ columns and $2^{|X_2|}$ rows, where each column and row has a label of unique binary code, and each element corresponds the truth value of f . In the decomposition chart, the column multiplicity denoted by μ is the number of different column patterns[†]. The function represented by a column pattern is a column function.

Example 3.3: Table 2 shows a decomposition chart of a 4-input 1-output incompletely specified function. Since all the column patterns are different, the column multiplicity is $\mu = 4$. (End of Example)

In a conventional functional decomposition using a BDD, the width of a BDD is equal to the column multiplicity μ . Let (X_1, X_2) be a partition of the input variables, then the nodes except for variables X_1 that are directly connected to the nodes for variables X_1 correspond to the column patterns in the decomposition chart. In a partition (X_1, X_2) , nodes representing column functions may have different heights. In a functional decomposition, such a relation is denoted by $f(X_1, X_2) = g(h(X_1), X_2)$. When $\lceil \log_2 \mu \rceil < |X_1|$, the function f can be decomposed into two networks: The first one realizes $h(X_1)$, and the second one realizes $g(h, X_2)$. The functional decomposition is effective when the number of inputs for g is smaller than that of f .

Definition 3.7: Two incompletely specified functions f and g are compatible, denoted by $f \sim g$, iff $f_{-0} \cdot g_{-1} = 0$ and $f_{-1} \cdot g_{-0} = 0$.

Lemma 3.1: Let χ_a and χ_b be the characteristic functions of two incompletely specified functions. If $\chi_a \sim \chi_b$ and $\chi_c = \chi_a \chi_b$, then $\chi_c \sim \chi_a$ and $\chi_c \sim \chi_b$.

Example 3.4: In the decomposition chart of Table 2, for pairs of column functions $\{\Phi_1, \Phi_2\}$, $\{\Phi_1, \Phi_3\}$, and $\{\Phi_3, \Phi_4\}$,

Table 3 Reduction of column multiplicity.

		$X_1 = \{x_1, x_2\}$			
		00	01	10	11
$X_2 = \{x_3, x_4\}$	00	0	0	1	1
	01	1	1	d	d
	10	1	1	0	0
	11	0	0	0	0
		Φ_1^*	Φ_2^*	Φ_3^*	Φ_4^*

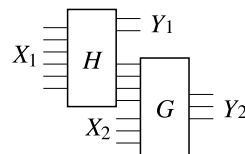


Fig. 3 Decomposition of multiple-output function.

the functions are compatible. Make the logical product of columns Φ_1 and Φ_2 , and replace them with Φ_1^* and Φ_2^* , respectively. Where, Φ_1^* and Φ_2^* show that the functions obtained by assigning constants to *don't cares*. Also, make the logical product of columns Φ_3 and Φ_4 , and replace them with Φ_3^* and Φ_4^* , respectively. Then, we have the decomposition chart in Table 3, where $\mu = 2$.

(End of Example)

The following theorem is similar to, but different from well known theorem on conventional functional decomposition using BDDs [8], [13]. It is an extension of [15] into incompletely specified functions.

Theorem 3.1: Let (X_1, Y_1, X_2, Y_2) be the variable ordering of the BDD_for_CF that represents the incompletely specified function, where X_1 and X_2 denote the disjoint ordered sets of input variables, and Y_1 and Y_2 denote the disjoint ordered sets of output variables. Let n_2 be the number of variables in X_2 , and m_2 be the number of variables in Y_2 . Let W be the width of the BDD_for_CF at height $n_2 + m_2$. When counting the width W , ignore the edges that connect the nodes of output variables and the constant 0. Suppose that the multiple-output function is realized by the network shown in Fig. 3. Then, the necessary and sufficient number of connections between two blocks H and G is $\lceil \log_2 W \rceil$.

3.2 Algorithm to Reduce the Width of a BDD_for_CF

Various methods exist to reduce the number of nodes in BDDs representing incompletely specified functions [3], [6], [21]–[23]. In the method [22], for each node, two children are merged when the functions represented by them are compatible. For example, when two children f and g in Fig. 4(a) are compatible, the BDD is simplified as shown in Fig. 4(b). By doing this operation repeatedly, we can reduce the number of nodes in the BDD. The following algorithm is used in our experiment, which is a simplified version of [22]. Note that our data structure is a BDD_for_CF instead of an SBDD.

[†]In the case of BDD_for_CF, we do not count the columns that consist of all zeros.

Algorithm 3.1: From the root node of the BDD, do the following operations recursively.

1. If the function represented by node v has no *don't care*, then terminate.
2. For v , check if two children v_0 and v_1 are compatible. Let the functions represented by v_0 and v_1 be χ_0 and χ_1 , respectively.
 - If they are incompatible, then apply this algorithm to v_0 and v_1 .
 - If they are compatible, then replace v_0 and v_1 with v_{new} , where v_{new} represents $\chi_{new} = \chi_0 \cdot \chi_1$, and apply this algorithm to v_{new} .

Example 3.5: Figures 5(a) and (b) show the BDD_for_CFs before and after the application of Algorithm 3.1, respectively. When there is only one edge coming down from a node, it denotes two edges that coincide. In Fig. 5(a), nodes 1 and 2 have compatible two children. For this function, the node replaced for node 1, and the node replaced for node 2 are the same. So, in Fig. 5(b), two nodes 1 and 2 are replaced with node 3. In the figures, the rightmost columns headed with “Width” denote the widths of the BDDs for each height. Note that the maximum width is reduced from 8 to 5, and the number of non-terminal nodes is reduced from 15 to 12. (End of Example)

The method in [22] is effective for local reduction of the number of nodes. However, since it only considers the compatibility of two children for each node at one time, it is not so effective to reduce the width of the BDD. Thus, in our method, we check the compatibility of column functions in each height, and perform the minimal clique cover of the functions to reduce the width of the BDD.

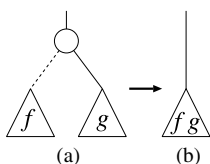


Fig. 4 Simplification method in [22].

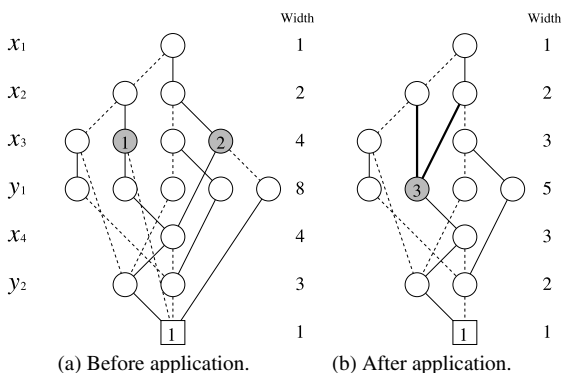


Fig. 5 BDD_for_CF before and after application of Algorithm 3.1.

Definition 3.8: In a compatibility graph, each node corresponds to a function, and an edge exists between nodes if the corresponding functions are compatible.

In the functional decomposition, check the compatibility of the column functions, and construct the compatibility graph. Then, minimize the column multiplicity μ by finding the minimum clique cover [3], [23]. Since this problem is NP-hard [5], we use the following heuristic method.

Algorithm 3.2: (Heuristic Minimal Clique Cover)

Let S_a be the set of all the nodes in the compatibility graph. Let C be the set of subset of S_a . From S_a , delete isolated nodes, and put them into C . While $S_a \neq \phi$, iterate the following operations:

1. Let v_i be the node that has the minimum number of edges in S_a . Let $S_i \leftarrow \{v_i\}$. Let S_b be the set of nodes in S_a that are connecting to v_i .
2. While $S_b \neq \phi$, iterate the following operations:
 - a. Let v_j be the node that has the minimum edges in S_b . Let $S_i \leftarrow S_i \cup \{v_j\}$. $S_b \leftarrow S_b - \{v_j\}$.
 - b. From S_b , delete the nodes that are not connected to v_j .
3. $C \leftarrow C \cup \{S_i\}$, $S_a \leftarrow S_a - S_i$.

Algorithm 3.3: (Reduction of Widths of a BDD_for_CF)

Let the height of the root node be t , and let the height of the constant nodes be 0. From the height $t - 1$ to 1, iterate the following operations:

1. Construct the set of all the column functions, and construct the compatibility graph.
2. Find the minimum clique cover for the compatibility graph by Algorithm 3.2.
3. For each clique, make a function by AND operation of all functions that corresponds the nodes of the clique.
4. For each column function, replace it with the function produced in step 3, and re-construct the BDD with a smaller width.

Example 3.6: Figure 6 shows the BDD_for_CF after applying Algorithm 3.3 to Fig. 2(b). At the height of x_3 , nodes 2 and 4 are compatible in Fig. 6(a). So, these nodes are merged into node **a** in Fig. 6(b). Next, at the height of y_1 , the compatibility graph is shown in Fig. 7. Note that in Fig. 6(c), nodes 6 and 8 are replaced by node **b**, and nodes 7 and 10 are replaced by node **c**. The resulting BDD is shown in Fig. 6(d). By comparing Figs. 6(a) and (d), we can see that the maximum width is reduced from 8 to 4, and the number of non-terminal nodes is reduced from 15 to 12. (End of Example)

3.3 Reduction of Support Variables

In incompletely specified functions, some variables can be redundant [14]. In this case, such support variables can be removed by appropriately assigning values to the *don't cares*. Reduction of the support variables often reduces the

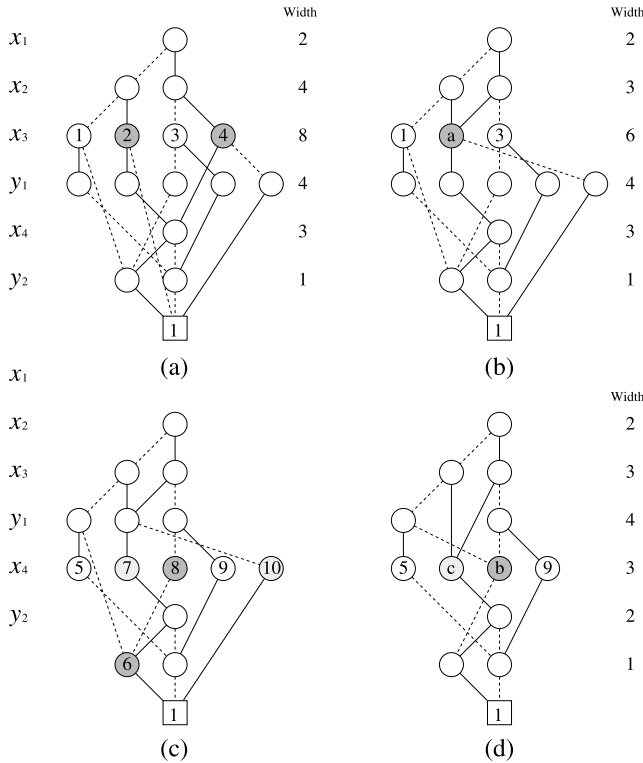


Fig. 6 Reduction of width of BDD_for_CF using Algorithm 3.3.

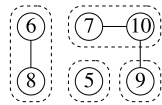


Fig. 7 Compatibility graph.

width of corresponding BDD_for_CF. Thus, we try to reduce support variables before applying Algorithm 3.1 or 3.3.

We use a greedy algorithm to reduce support variables. For each height in the BDD_for_CF, check whether the variable is redundant or not. Next, if it is redundant, then we delete the variable by appropriately assigning values to the *don't cares*. We apply the operation from the root to the leaf nodes.

4. Benchmark Functions

To evaluate the performance of Algorithm 3.3, we used the following incompletely specified functions.

4.1 Arithmetic Functions [17]

- Residue number to binary number converters.
- p -nary to binary converters.
- Decimal adders and multiplier.

Each of these functions represents a mapping $f : P_0 \times P_1 \times \dots \times P_{k-1} \rightarrow Q$, where $P_i = \{0, 1, \dots, p_i - 1\}$ and $Q = \{0, 1, \dots, q - 1\}$. In these benchmark functions, binary-coded- p_i -nary codes are used to represent p_i -nary digits. When p_i

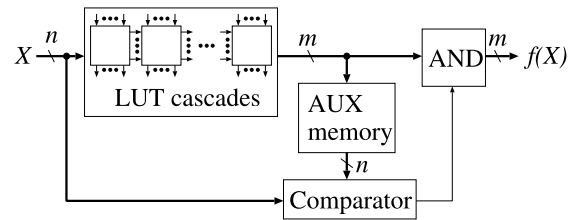


Fig. 8 Realization of English word list by using LUT cascade and AUX memory.

is not a power of 2, the p_i -nary digit has unused input combinations. In this case, we assign *don't cares* to the undefined outputs. We call such *don't cares* as input *don't cares*.

Let us consider the ratio of these *input don't cares* for benchmark functions. Note that each digit of a p_i -nary number uses $b_i = \lceil \log_2 p_i \rceil$ bits. Thus, the ratio of *input don't cares* is $\frac{2^{b_i} - p_i}{2^{b_i}} = 1 - \frac{p_i}{2^{b_i}}$, since each variable uses only p_i combinations out of 2^{b_i} . For a benchmark function with k digits, the ratio of *input don't cares* is

$$1 - \prod_{i=0}^{k-1} \frac{p_i}{2^{b_i}}.$$

Example 4.7: Consider the 10-digit ternary to binary converter. Assume that binary-coded-ternary is used to represent a ternary digit: 0 is represented by (00); 1 is represented by (01); and 2 is represented by (10). (11) is an undefined input, and the corresponding outputs are *don't cares*. Note that $p_0 = p_1 = p_2 = 3$, $b_0 = b_1 = b_2 = 2$, and $k = 10$. Thus, only $(\frac{3}{4})^{10} = 0.0563$ of the input combinations are specified, and the remaining $1 - (\frac{3}{4})^{10} = 0.9437$ of the combinations are unspecified. (End of Example)

4.2 English Word Lists [19]

We considered logic functions that represent three lists of English words [19] (Details are shown in Sect. 5.3.). For the English words consisting of fewer than 8 letters, we append blanks to the end of words to make them 8-letter words. Each English alphabet letter is represented by 5 bits, and each English word is represented by $n = 40$ bits. The numbers of words in the three lists are 1730, 3366, and 4705, respectively. In each word list, each English word has a unique index of an integer from 1 to k , where $k = 1730$ or 3366 or 4705. In this case, the outputs for undefined inputs are assigned to 0. The numbers of bits to represent the indices are $m = 11, 12,$ and 13 , respectively. Such a function denotes a mapping $f : P^8 \rightarrow Q$, where $P = \{0, 1, \dots, 26\}$ and $Q = \{0, 1, \dots, k\}$. In this case, the ratio of *input don't cares* is $1 - (\frac{27}{25})^8 = 0.74$.

In the realization shown in Fig. 8 [19], we can replace the output 0 with *don't care*. In this case, the ratio of *don't cares* will be increased to $1 - \frac{k}{2^{40}}$. Note that for our benchmark function, only k different input combinations are

mapped to integers from 1 to k , and other $(2^n - k)$ input combinations are mapped to *don't cares*. In Fig. 8, an English word list is implemented by using LUT cascades and an auxiliary memory [19]. The auxiliary memory checks whether output is correct or not. With this method, we can drastically reduce the size of the cascade.

5. Experimental Results

5.1 Reduction of BDD Width

We applied Algorithms 3.1 and 3.3 to each of the incompletely specified function presented in Sect. 4, and reduced the widths of the BDD_for_CF. Before applying algorithms, we optimized the order of the variables in the BDD_for_CF by sifting algorithm [12], where the sum of the widths is used as the cost function.

When all the output functions are represented by a single BDD_for_CF, the circuits were too large to implement. Handling many outputs at a time makes it difficult to find 0-1 assignments that simplify the BDD_for_CF. On the other hand, splitting outputs makes it easier to find 0-1 assignment to *don't cares*. However splitting all the outputs into single will conflict the optimization of multiple-output function. Similar things happen in the minimization of sum-of-products expressions for multiple-output functions. So, we partitioned the outputs into two sets, and represented each of them by a BDD_for_CF separately. Table 4 shows the maximum widths of the BDD_for_CF and

the number of nodes when the multiple-output function $F = (f_1, \dots, f_m)$ is partitioned into two: $F_1 = (f_1, \dots, f_{\lfloor m/2 \rfloor})$ and $F_2 = (f_{\lfloor m/2 \rfloor + 1}, \dots, f_m)$. The upper numbers denote the values for F_1 , and the lower numbers denote the values for F_2 .

In the table, the column headed by *In* denotes the number of inputs; *Out* denotes the number of outputs; *DC* denotes the ratio of *don't cares*; $DC = 0$ denotes the case where constant 0's were assigned to all the *don't cares*; $DC = 1$ denotes the case where constant 1's were assigned to all the *don't cares*; *ISF* denotes the case where incompletely specified functions (ternary functions) were represented; *Alg3.1* denotes the case where Algorithm 3.1 was applied; *Alg3.3* denotes the case where Algorithm 3.3 was applied; and *Time* denotes the computation time for Algorithms 3.1 and 3.3. Reduction ratio was normalized to 1.00 for the case of $DC = 0$.

By partitioning the outputs into two sets, we could drastically reduce the sizes of the BDDs for all the functions. For some functions, the maximum width of the BDD became less than 1/100 of the original BDD, and the total number of nodes became less than 1/30. With bi-partitions of outputs, we could implement the circuits with reasonable sizes.

Table 4 shows that Algorithm 3.3 produced BDDs with smaller widths than Algorithm 3.1, especially for F_2 , the outputs for the least significant bits. Algorithm 3.1 checks only the compatibility of two children for each node, and reduces the number of nodes locally. On the other hand, Al-

Table 4 Maximum width and number of nodes in BDD_for_CF.

Function	In	Out	DC [%]	Maximum width				# of nodes					Time [Sec]		
				DC=0	DC=1	ISF	Alg3.1	Alg3.3	DC=0	DC=1	ISF	Alg3.1	Alg3.3	Alg3.1	Alg3.3
5-7-11-13 RNS	14	13	69.5	426	426	426	425	395	2208	2220	2214	1983	1906	0.011	0.156
				375	375	375	374	320	2022	2022	2028	1742	1741		
7-11-13-17 RNS	16	15	74.0	450	450	450	449	316	2974	2985	2978	2444	2316	0.033	0.562
				897	897	897	896	896	4730	4730	4737	4254	4073		
11-13-15-17 RNS	17	16	72.2	1259	1259	1259	1258	777	6830	6845	6838	6271	4576	0.063	2.437
				2143	2144	2144	2143	1231	9870	9871	9877	9019	7114		
4-digit 11-nary to binary	16	14	77.7	117	117	117	116	115	1223	1227	1223	1086	1203	0.017	0.094
				256	256	257	256	128	1931	1931	1935	1582	1328		
4-digit 13-nary to binary	16	15	56.4	226	226	226	225	224	2293	2299	2293	2150	2288	0.031	0.078
				257	257	257	256	128	2231	2231	2235	1821	1456		
5-digit 10-nary to binary	20	17	90.5	393	393	393	392	391	3260	3267	3260	2794	3251	0.032	0.154
				257	257	78	76	64	2322	2322	593	527	439		
6-digit 5-nary to binary	18	14	94.0	134	134	134	133	129	1442	1445	1442	1215	1432	0.030	0.063
				257	257	257	256	128	1875	1875	1878	1373	1337		
6-digit 6-nary to binary	18	16	82.2	185	185	189	188	184	1310	1317	1367	1185	1328	0.032	0.015
				257	257	89	64	32	1849	1849	445	299	307		
6-digit 7-nary to binary	18	17	55.1	464	464	464	463	463	4917	4923	4917	4566	4826	0.093	0.421
				513	513	513	512	256	4723	4723	4726	3901	3177		
10-digit 3-nary to binary	20	16	94.4	265	265	265	264	240	2814	2819	2814	2342	2782	0.063	0.328
				513	513	513	512	256	4005	4005	4007	2842	2961		
3-digit decimal adder	24	16	94.0	27	27	14	13	10	187	207	129	93	109	0.046	0.000
				200	101	14	13	10	1643	1035	125	95	108		
4-digit decimal adder	32	20	97.7	79	79	14	13	10	487	509	176	128	152	2.875	0.015
				1398	649	14	13	10	10047	5764	177	136	160		
2-digit decimal multiplier	16	16	84.7	945	946	955	945	945	3013	3020	3035	2716	2980	0.014	0.124
				499	505	193	192	192	2776	2790	1330	1193	1257		
1730 words	40	11	99.9	866	901	735	383	100	16900	17321	9433	1140	954	0.031	0.486
				834	836	843	427	149	16616	16670	11478	1698	2121		
3366 words	40	12	99.9	1322	1337	1325	634	192	17534	17710	14931	1990	2205	0.063	1.704
				1709	1713	1729	975	441	25434	25446	21510	3428	4729		
4705 words	40	13	99.9	2025	2042	1895	751	213	33556	33923	27484	2438	2255	0.078	2.673
				2188	2185	2182	1161	385	40627	40506	35159	4561	6027		
Ratio				1.000	0.970	0.833	0.735	0.540	1.000	0.982	0.807	0.580	0.583		

Table 5 Reduction of LUT cascades by using *don't cares*.

Function	DC=0			Alg3.3		
	#Cel	#LUT	#Cas	#Cel	#LUT	#Cas
5-7-11-13 RNS	6	35	3	4	29	2
7-11-13-17 RNS	9	53	3	8	50	3
11-13-15-17 RNS	—	—	—	24	118	8
4-digit 11-nary to binary	4	29	2	4	28	2
4-digit 13-nary to binary	4	31	2	4	30	2
5-digit 10-nary to binary	8	50	3	6	48	2
6-digit 5-nary to binary	6	44	2	5	35	2
6-digit 6-nary to binary	5	33	2	4	29	2
6-digit 7-nary to binary	9	62	3	8	54	3
10-digit ternary to binary	9	58	3	6	48	2
3-digit decimal adder	6	35	2	3	17	1
4-digit decimal adder	9	62	2	4	24	1
2-digit decimal multiplier	8	51	3	7	48	3

gorithm 3.3 checks compatibilities among all the functions for each height of a BDD, to reduce the width more effectively. Let w be the width of the BDD, then the algorithm checks $(w^2 - w)/2$ compatibilities. Also, Algorithm 3.3 finds the minimal clique cover, so it is more time-consuming than Algorithm 3.1.

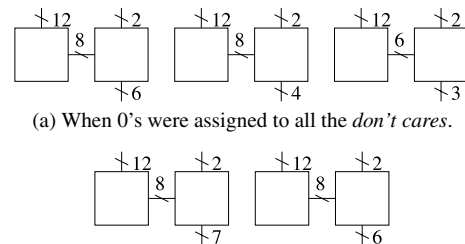
We used gcc version 3.2 compiler on a PC having Athlon64 (2.6 GHz) with 2 GByte memory. The longest CPU times were as follows: When all the outputs were represented by a single BDD_for_Cf: 110 sec (the list of 4705 English words) to generate BDD_for_Cf. 2433 sec (6-digit 7-nary to binary converter) to reduce the width of the BDD. When the outputs are bi-partitioned: 3.2 sec (11-13-15-17 RNS) to generate a pair of BDD_for_Cfs. 2.4 sec (11-13-15-17 RNS) to reduce the widths of BDD_for_Cfs.

5.2 Optimization of LUT Cascades

In the functional decomposition, when the width of the BDD is slightly larger than 2^k , by properly assigning the constants to *don't cares*, we can often reduce the width of the BDD, and reduces the number of interconnections between two blocks H and G in Fig. 3.

To see the usefulness of Algorithm 3.3, we designed benchmark functions in Sect. 4 by LUT cascades [15]. Table 5 shows the sizes of LUT cascades. For benchmark functions, we used cells with at most 12 inputs and at most 8 outputs to implement the cascades [11]. In Table 5, #Cel denote the number of cells in the cascade; #LUT denotes total number of LUT outputs; and #Cas denotes the number of cascades. The symbol ‘—’ shows that the function could not be realized by LUT cascades.

For example, consider 5-7-11-13 RNS. In this function, 69.5% of the input combinations are *don't cares*. Figure 9(a) shows the case where constant 0's were assigned to all the *input don't cares*, while Fig. 9(b) shows the case where Algorithm 3.3 was used to assign *don't cares*. Algorithm 3.3 produced smaller cascades: On the average, the total numbers of cells is reduced by 22.4%, the total number of cell outputs is reduced by 17.9%, and the total numbers of cascades is reduced by 16.7%. We also designed cascades by using Algorithm 3.1. In this case, the reduction rates were, 16.4%, 14.6%, and 13.9%, respectively. So, Algorithm 3.1 was not so effective as Algorithm 3.3.

**Fig. 9** 5-7-11-13 RNS to binary number converters.**Table 6** Realization of English word lists.

Design Method	# of words	#Cel	#LUT	#Cas	#RV	MemBits	
						LUT	AUX
DC=0	1730	26	237	2	0	954,624	0
	3366	60	475	6	0	1,892,416	0
	4705	132	1094	12	0	4,279,936	0
Fig. 8	1730	5	36	1	9	110,592	81,920
	3366	11	77	2	9	258,048	163,840
	4705	14	100	2	3	310,272	327,680

5.3 Realization of English Word Lists by LUT Cascade and Auxiliary Memory

We designed English word lists by the architecture in Fig. 8. Although this architecture requires the auxiliary memory with n^{2m} bits, we can drastically reduce the number of cells and number of memory bits for LUT cascades. Hence, we have a faster circuit. By replacing the output 0 with *don't care*, we often have a function with redundant variables. If the cascade consists of a single memory, reduction of i variables reduces the size of memory into $\frac{1}{2^i}$.

Table 6 shows the size of LUT cascades and auxiliary memory. In Table 6, $DC = 0$ denotes the case where circuits were designed by only LUT cascades; Fig. 8 denotes the case where circuits were designed by architecture in Fig. 8; #Cel denote the number of cells in the cascade; #LUT denotes total number of LUT outputs; #Cas denotes the number of cascades; #RV denotes the number of redundant variables; LUT in MemBits denotes the total memory bits for LUT cascades; and AUX in MemBits denotes the memory bits for a auxiliary memory. To implement the cascade, the case of $DC=0$ requires 12-input 10-output cells. Thus, we used cells with at most 12 inputs and at most 10 outputs.

Table 6 shows that the total number of LUT outputs is reduced by 83.8% to 90.9%; the total number of cells is reduced by 80.8% to 89.4%; the number of memory bits for LUT cascades is reduced by 86.4% to 92.8%; and the number of memory bits including the auxiliary memory is reduced by 77.7% to 85.1%. We could remove 9 variables for the lists of 1730 word and 3366 word, and could remove 3 variables for the lists of 4705 word.

6. Concluding Remarks

In this paper, we first showed a new method to represent an incompletely specified multiple-output function by

a BDD_for_CF. Second, we presented a method to reduce the width of the BDD. Third, we applied this method to radix converters, adders, a multiplier, and lists of English words. When all the outputs were represented by a single BDD_for_CF, we could not reduce the width of the BDD even if we use the *don't cares*. However, when the outputs were partitioned into two sets, and each set was represented by a BDD_for_CF, we could reduce the width of the BDD by using *don't cares*. We also applied this method to design LUT cascades. By using the method, we could reduce the numbers of cells in cascades, on the average, by 22.4%.

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